

openboards

Voltboard QuickStart Guide

For this guide, you will need:

- OP3 w/ NEOS connected via SSH w/ "root" access

1. Get the Gear (openboards.io/volt)
2. Flash the OP3 (1. <http://bit.ly/2CitAbm> 2. <http://bit.ly/2BU8nZf> 3. <http://bit.ly/2EjCmax>)
3. Flash the Voltboard, & Panda (<http://bit.ly/2Bnu3fs>)
4. Put the neo case together (<http://bit.ly/2o3bMeX>)
5. Make the Voltboard Interface Cable (<http://bit.ly/2EkXg9x>)
6. Install the voltboard + case
7. Disconnect the stock camera, plug in the interface cable and connect to voltboard.
8. Plug in panda
9. Go to the back of the vehicle and unplug the left connector from the ascm.
10. Bridge the pins on the ASCM. (<http://bit.ly/2nZ9X2G>)

Congrats! You should now have a self-driving Chevrolet Volt!

For pinout, installation, or cable guides, checkout: <http://openboards.io/resources/> for more information. Happy Hacking!